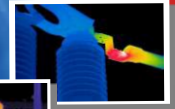
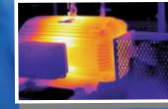


Infrared Imaging

Digital Imaging Systems, lecture 15

January 2009

Malin Ingerhed



IR basics

Applications

Detector technologies

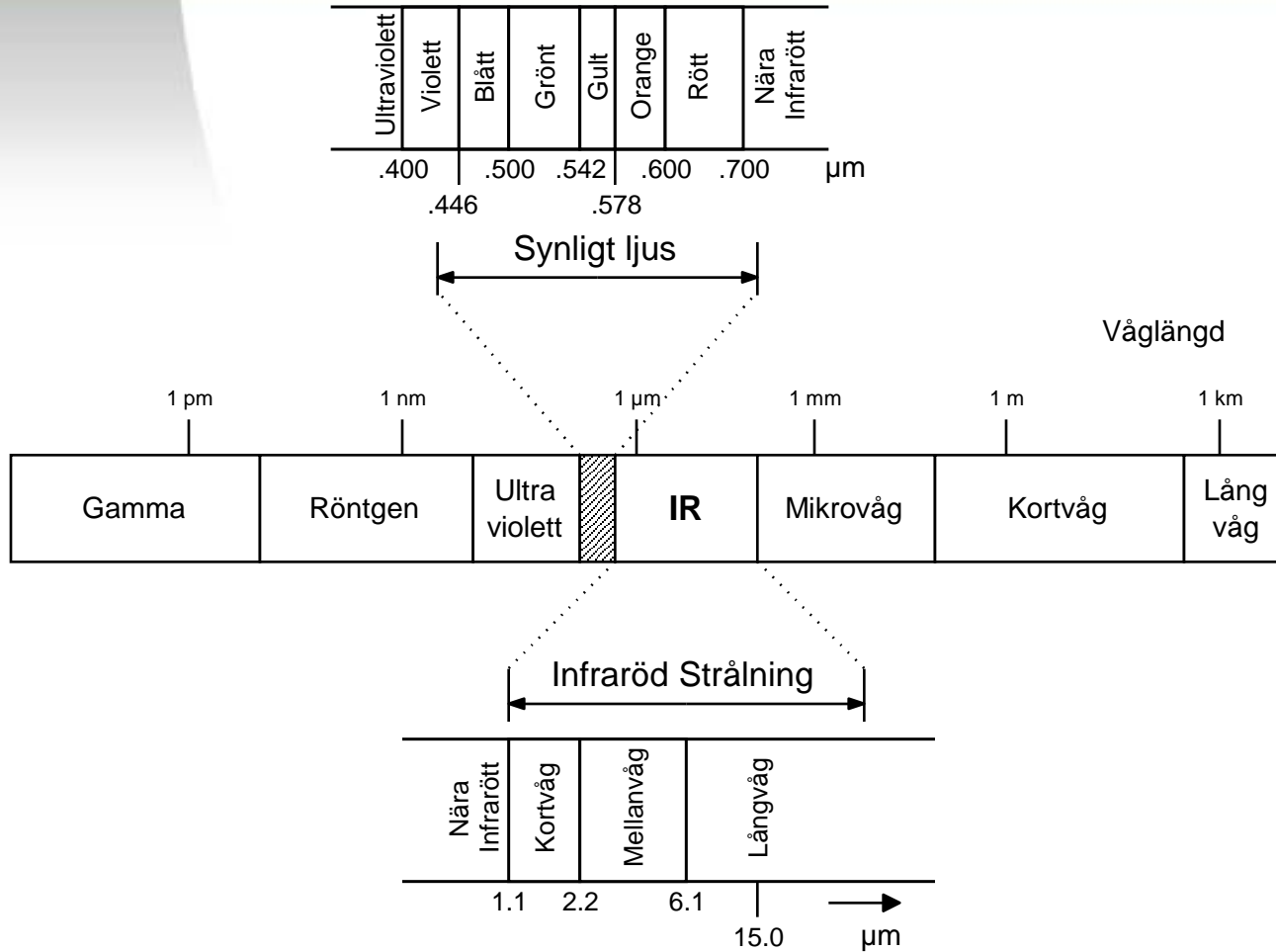
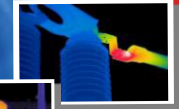
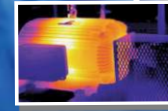
Data processing

Image quality

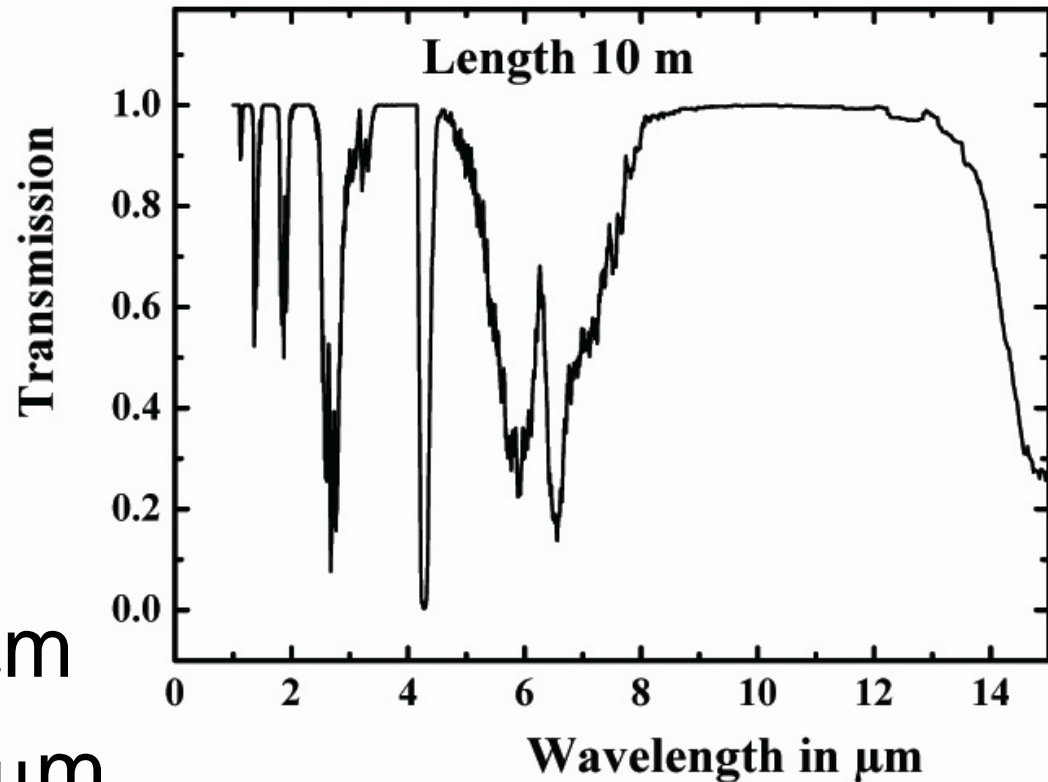
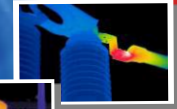
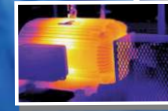
Quick course in data sheet reading

Future development

Infrared spectrum

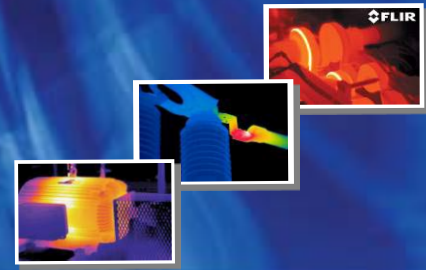


Transmission in air

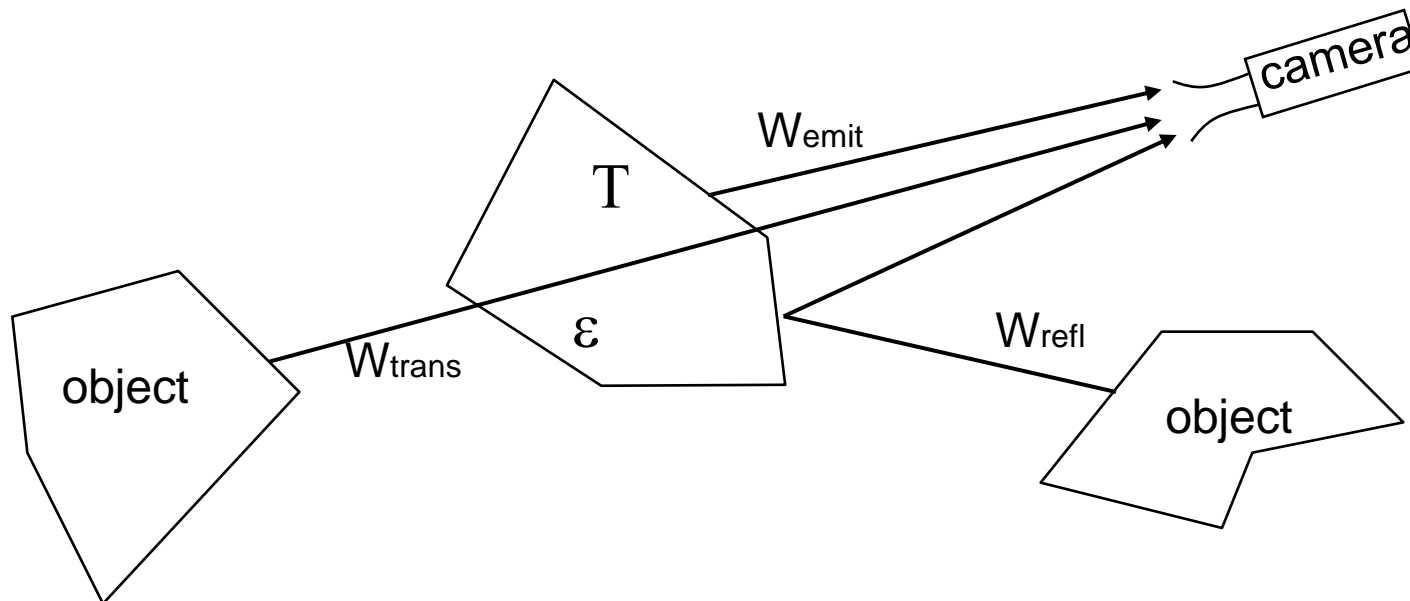


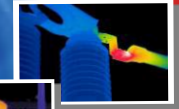
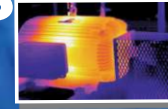
Shortwave: 2-5 μm

Longwave: 8-14 μm



Radiation captured by the camera consists of reflected, transmitted and emitted radiation.





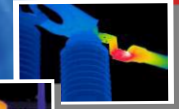
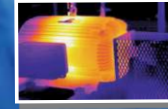
Transmission is usually not a problem, very few materials are transparent enough in IR



Reflection is a large problem

Large effect on measurements

Difficult to avoid

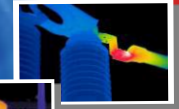
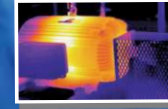


The emission from an object depends on the object temperature, T , and the emissivity, ϵ , of the object.

Emissivity depends on the material. Surface usually have large importance.

Emissivity is a user adjusted parameter in the camera that must be correct to get correct measurements

Radiometric cameras (thermography cameras)

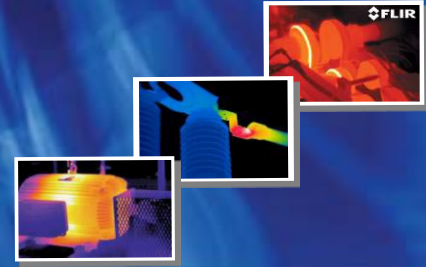


Temperature measuring cameras.

Needs: Calibration
 Temperature compensation

Temperature cycling during production gives parameters for temperature compensation.

Individual calibration of each camera



Different kinds of surveillance

Airborne

Maritime

Landborne

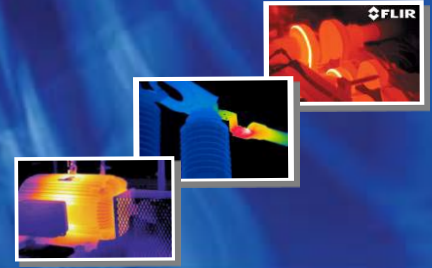


Semi-military application

Border control



Thermography cameras



NEC

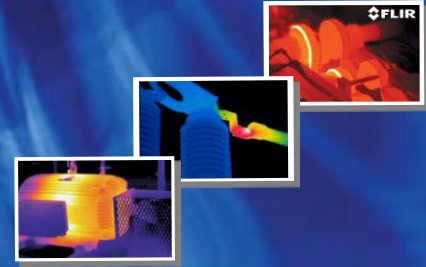


FLIR



FLUKE





Three market segments

High volume: Low resolution, low framerate, low price

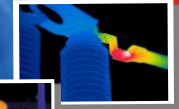
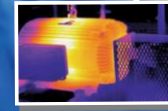


High end: Good image quality, lots of features, high price

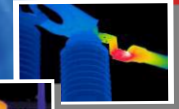
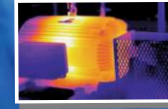


R&D: High framerate, long recording, very good image quality, expensive

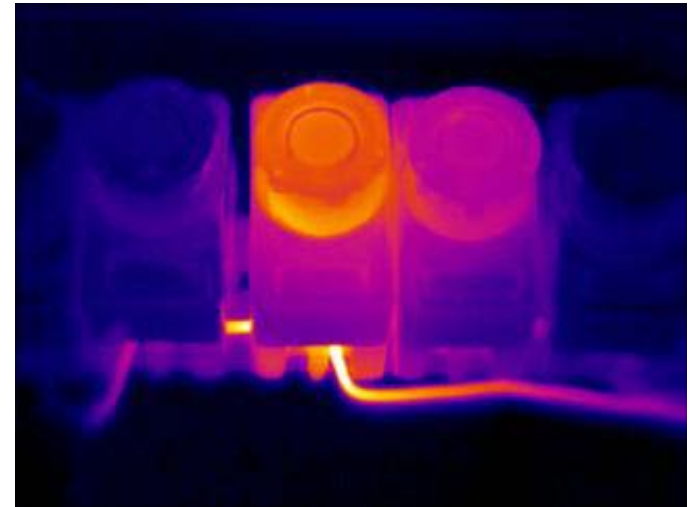
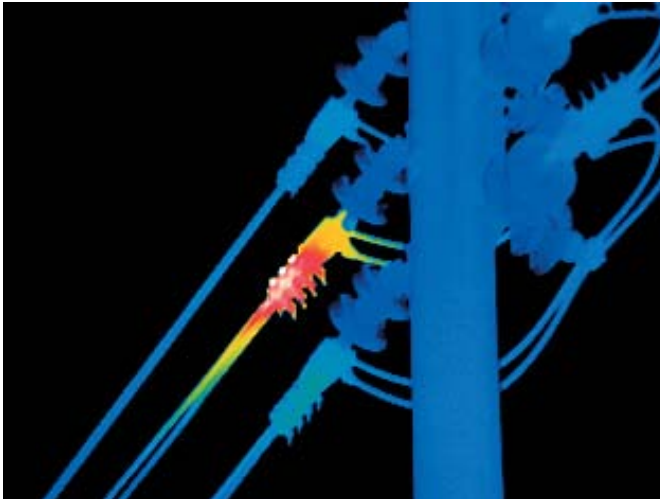


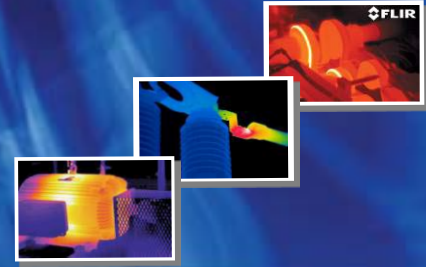


Electrical
Building
Energy saving
Gas detection
Night vision, cars and boats
Automation
Security
R&D

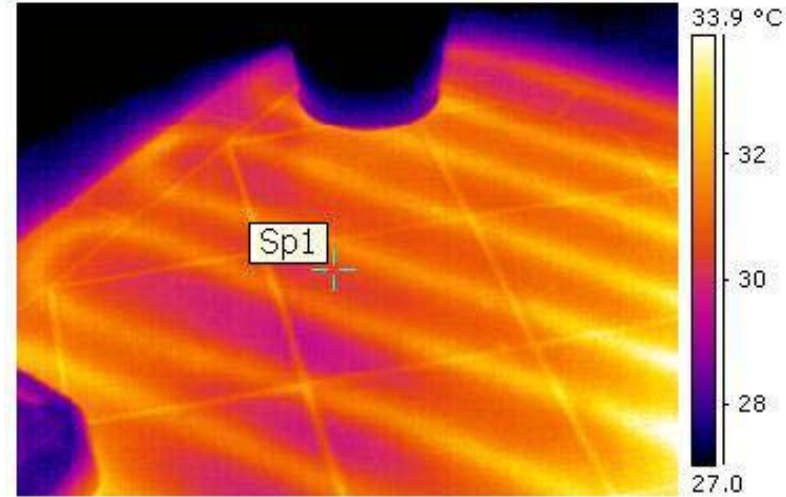


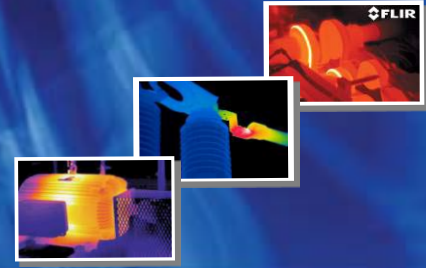
The oldest commercial application



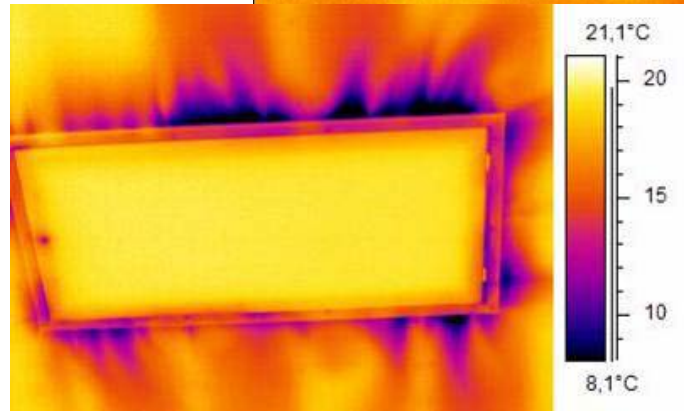
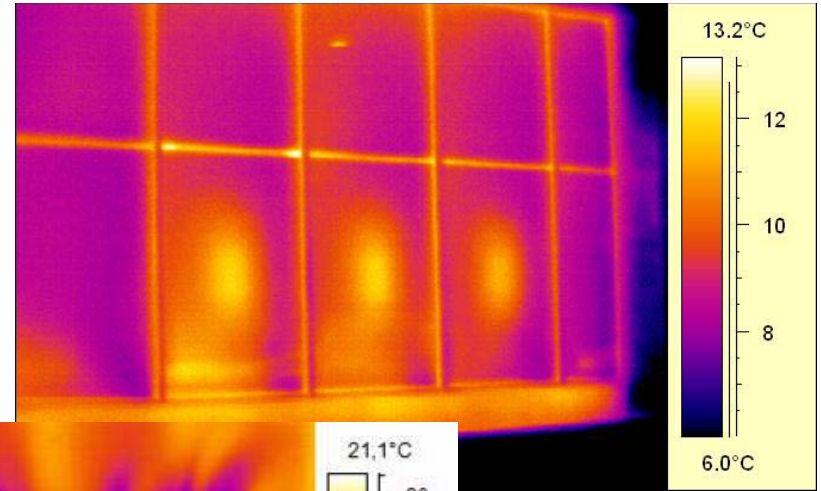
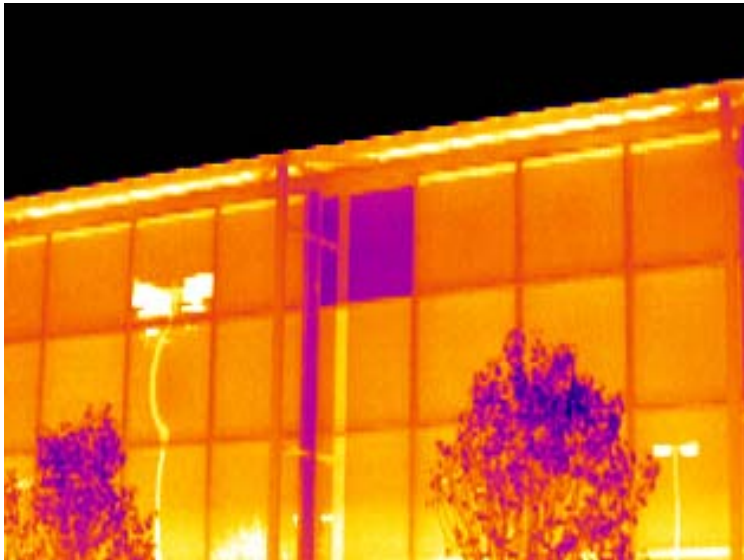


Fastly growing application

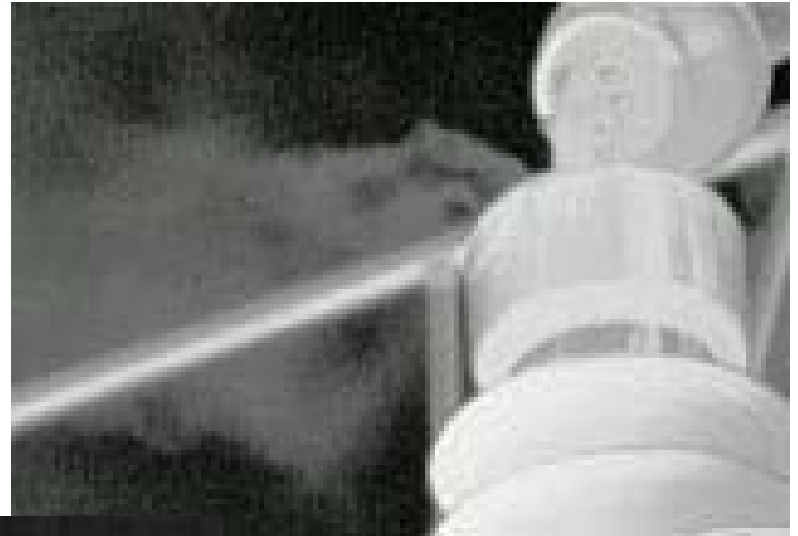
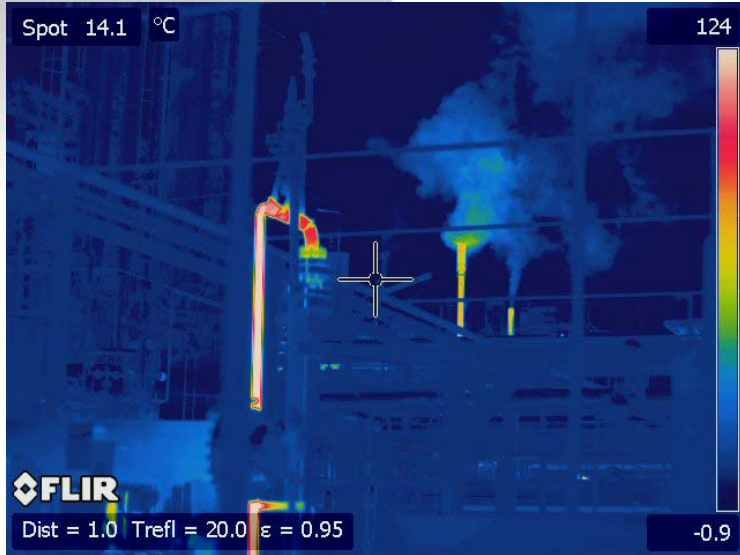
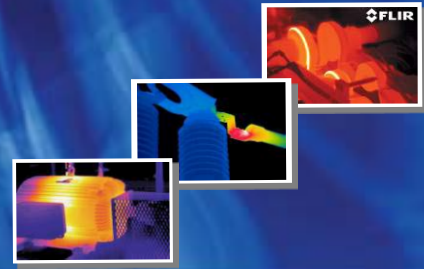


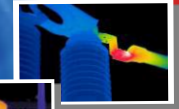
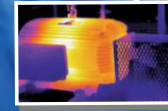


According to EU regulations all buildings must have an energy declaration



Gas detection





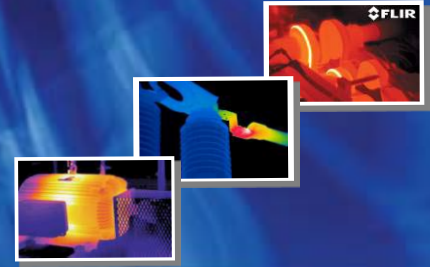
A number of commercially important gases can be detected. Different gases is visible in different wave lengths due to absorption characteristics of the gas.

Special cameras with very narrow wave-length used

Example of gases visible in mid-wave

Benzene	Pentane
Ethanol	1-Pentene
Ethylbenzene	Toluene
Heptane	Xylene
Hexane	Butane
Isoprene	Ethane
Methanol	Methane
MEK	Propane
MIBK	Ethylene
Octane	Propylene

Visible in long wave: Most important SF₆

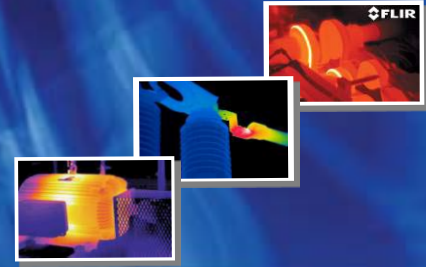


Cars: pedestrian avoidance

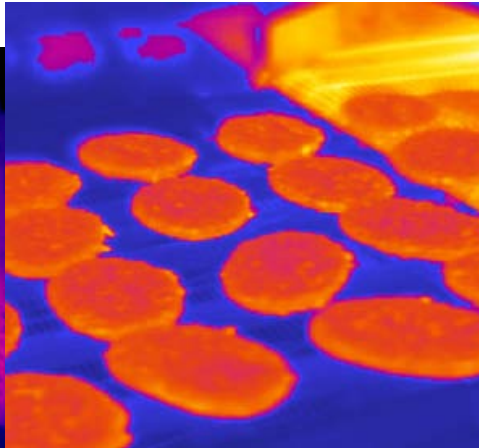
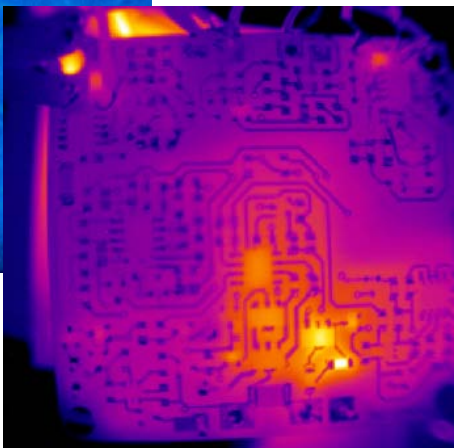
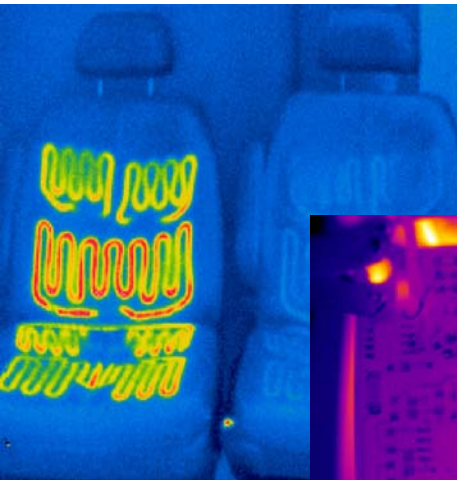


Boats: navigation search-and-rescue

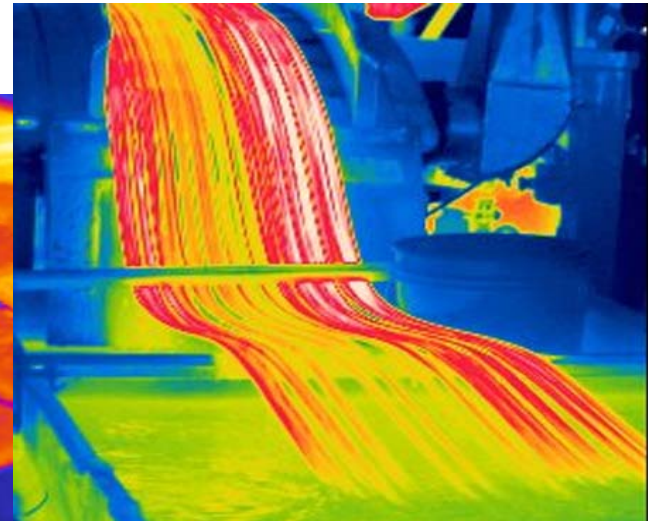




A wide range of different areas
IR-cameras often part of a large system for
quality assurance and fault detection

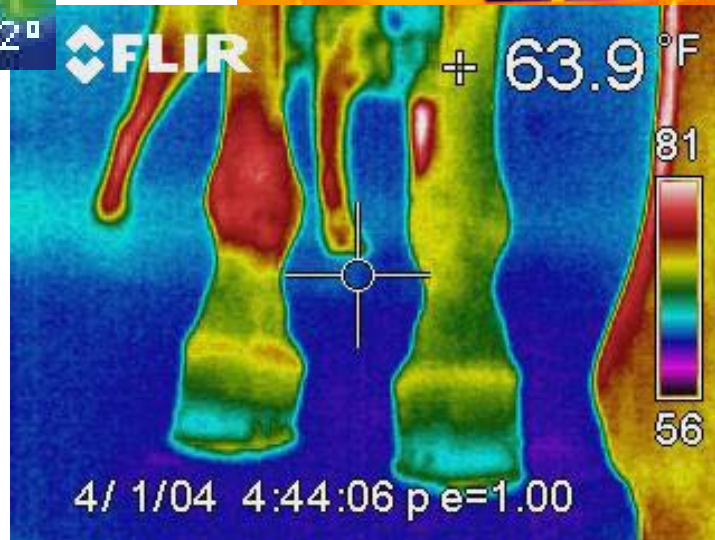
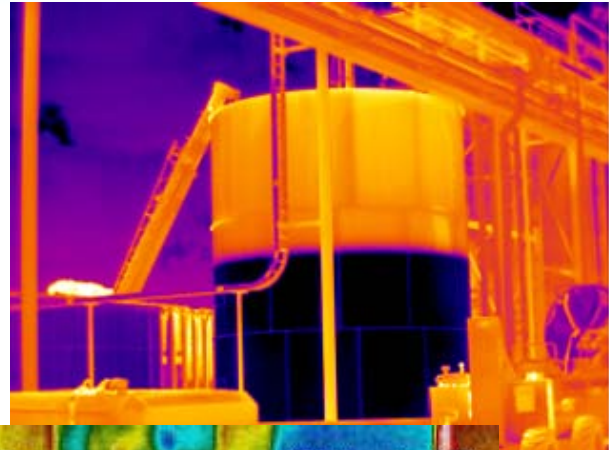
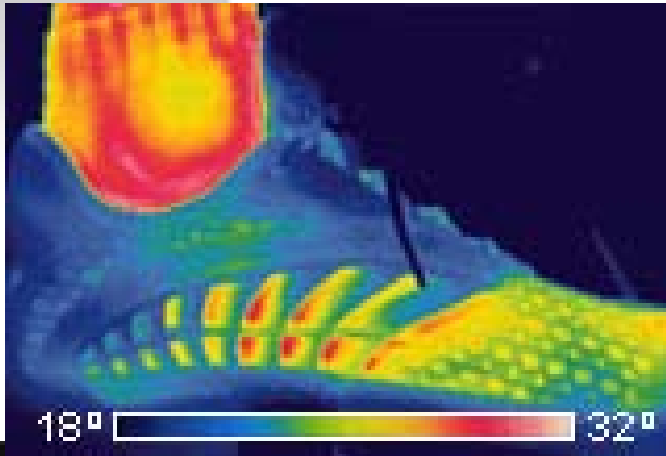
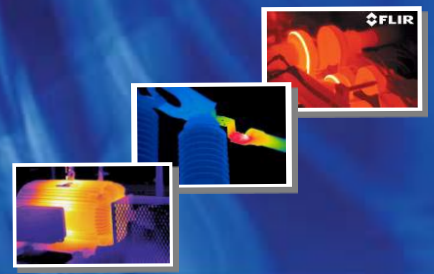


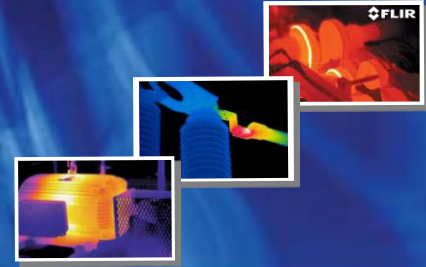
257C





The Global Leader in Infrared Cameras

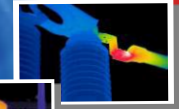
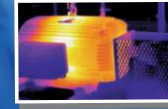




Early IR cameras were scanning systems
One single detector element received radiation from all points in the scene by projecting the points on to the detector

Cameras with
2D detectors
(FPA) introduced
around 1990





Uncooled detectors

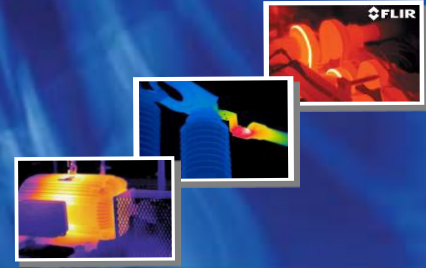
Micro bolometer, amorphous silicon
VOX

Cooled detectors

InSb

QWIP

MCT

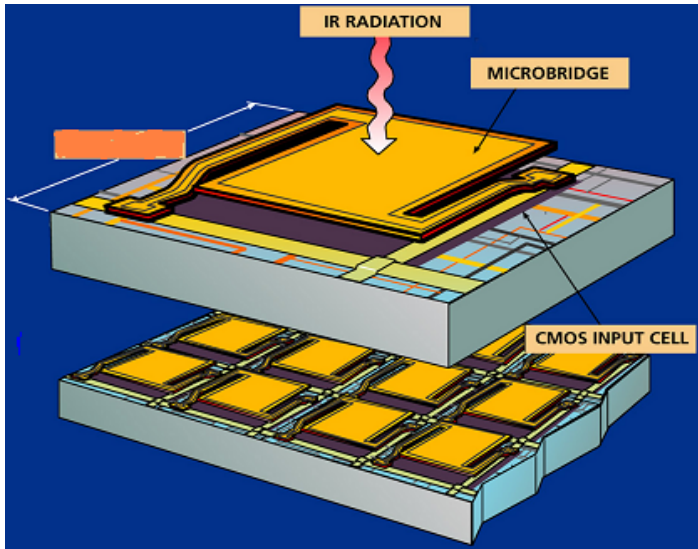


Bolometers resistance decrease when bolometer temperature increase

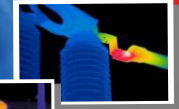
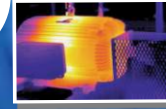
Two different materials:
amorphous silicon, VOX

Uncooled

Wavelength 8-14 μ m



InSb (Indium Antimonide)

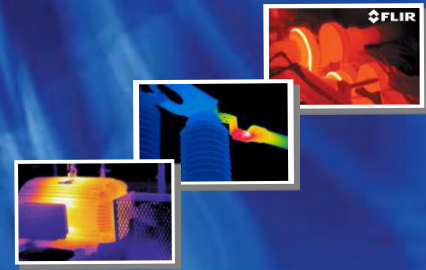


InSb

generates current when exposed to infrared radiation

Operating temperature: 80 K

Wavelength: visible-5,5 μm



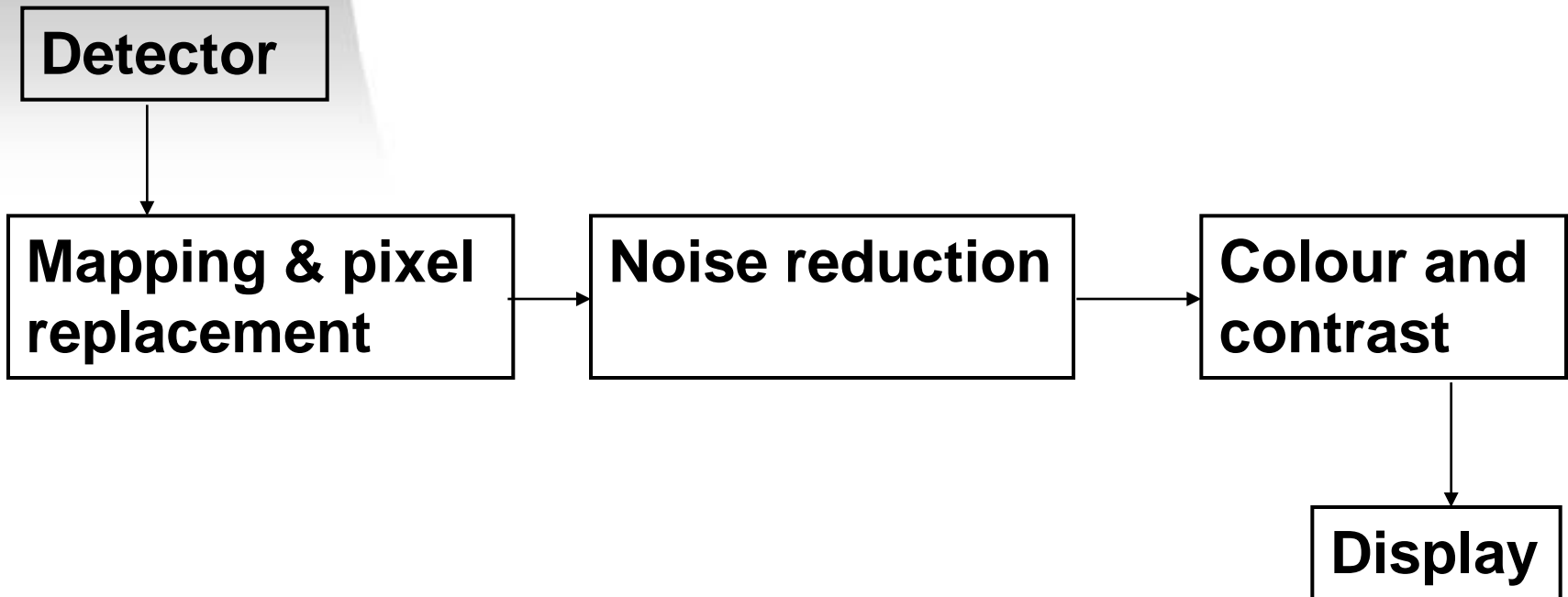
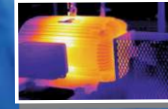
QWIP = Quantum Well Infrared Photodetectors

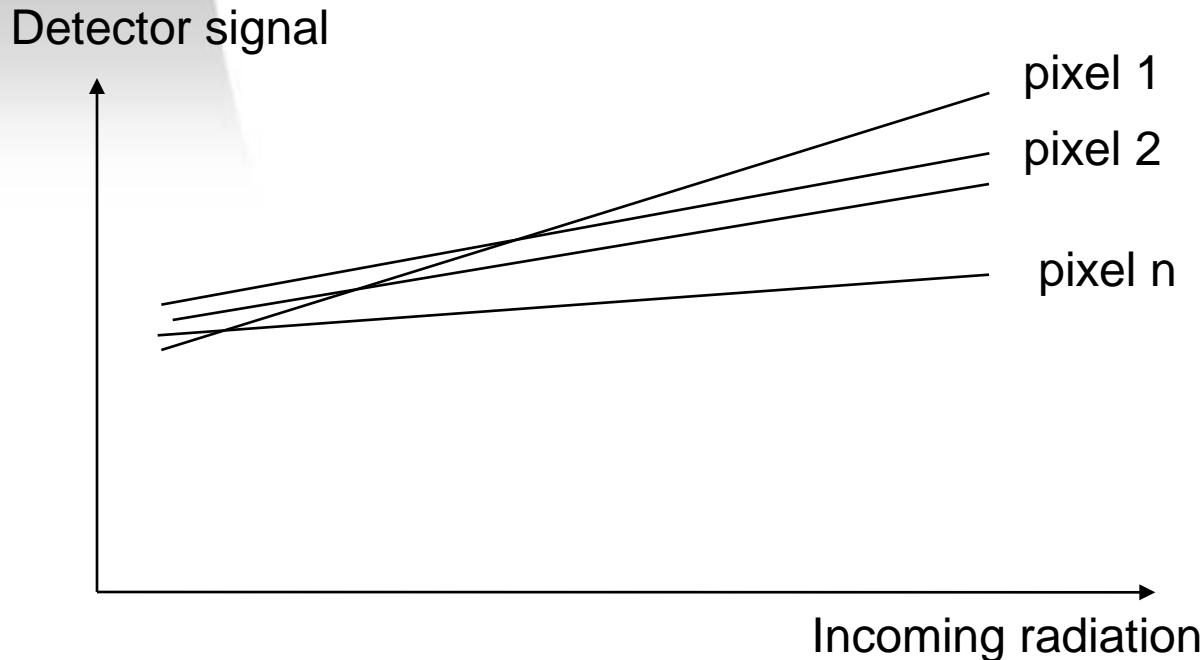
Output signal proportional to number of infalling photons

Different materials and material structures gives different wavelenghts.

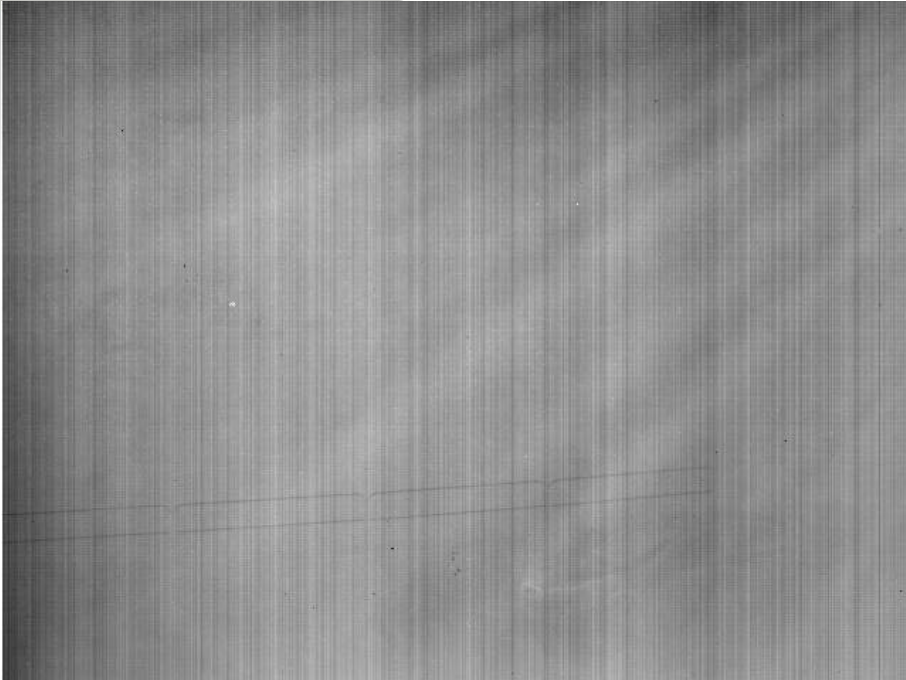
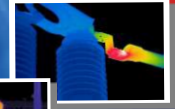
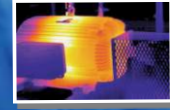
Different operating temperatures for different wavelenghts. 50-70K

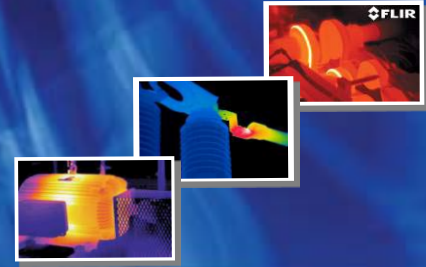
Data processing from detector to display





Necesssary with pixelvise gain and offset compensation $I(x,y) = a(x,y)*I_o(x,y)+b(x,y)$

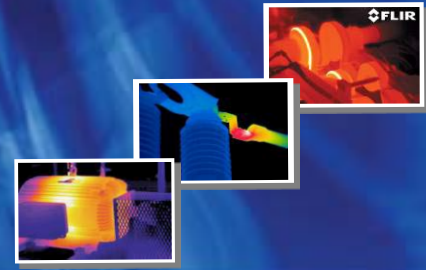




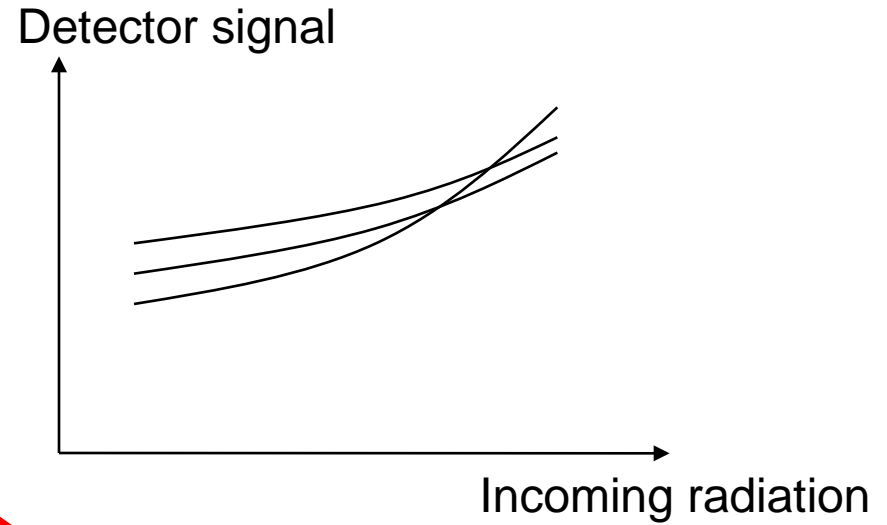
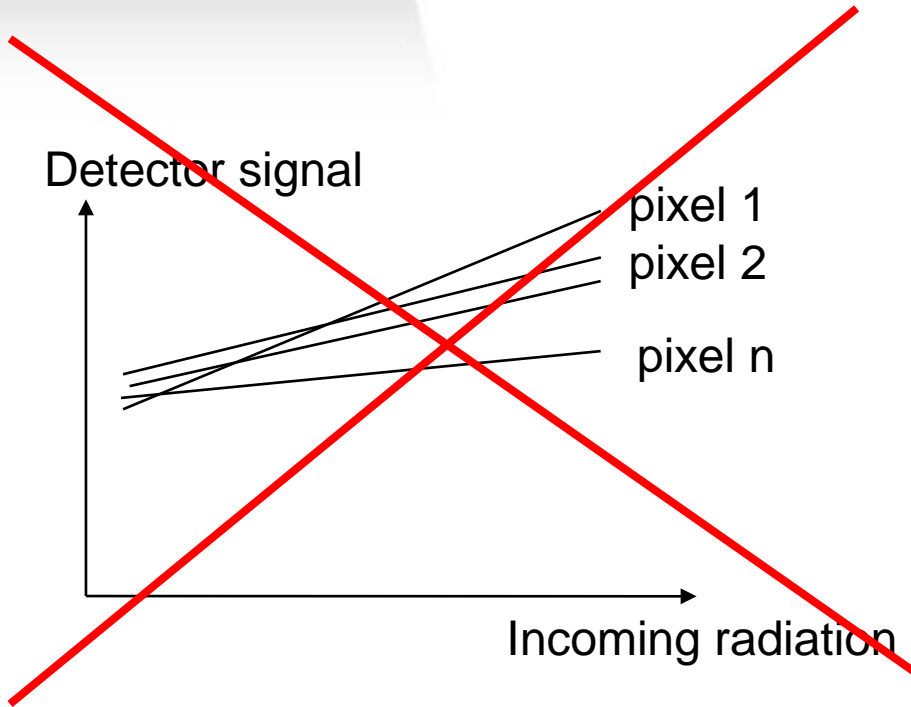
Usually: Maps computed and stored in the camera during production.

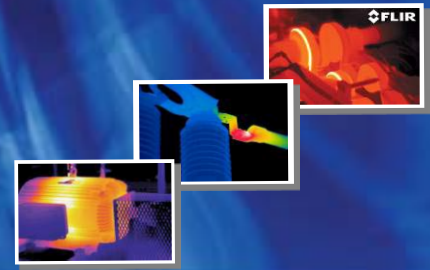
Additional offset correction map computed during use of the camera.

The offset map is computed using a shutter flag.



Detector elements non-linear



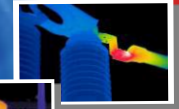
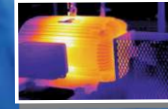


Pixels from low quality detector elements must be replaced.

The main problem is detection of these pixels. Pixels can be bad in many different ways.

Examples of types of bad pixels: spatial, temporal, gain deviation

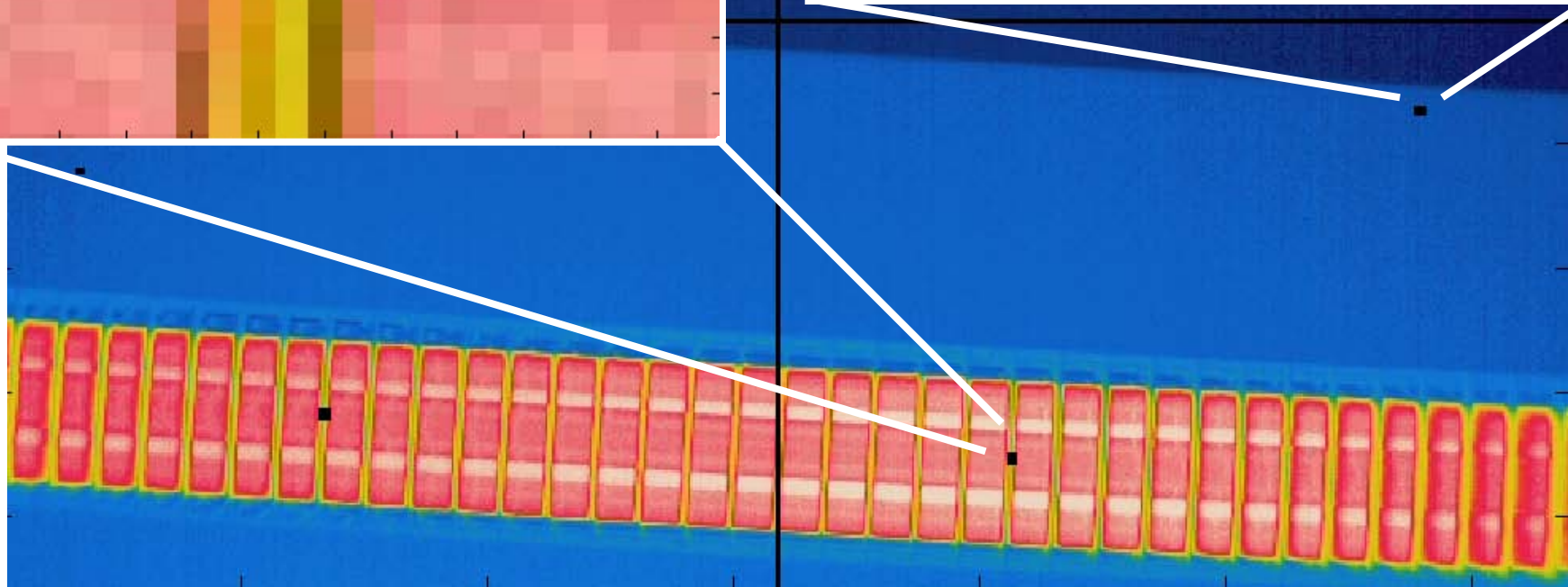
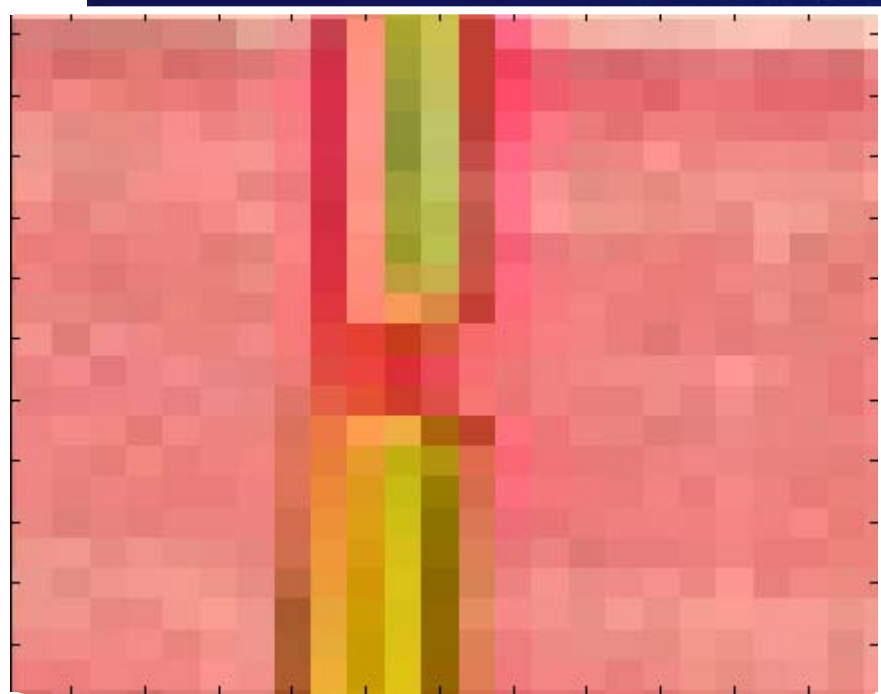
Detection of bad pixels

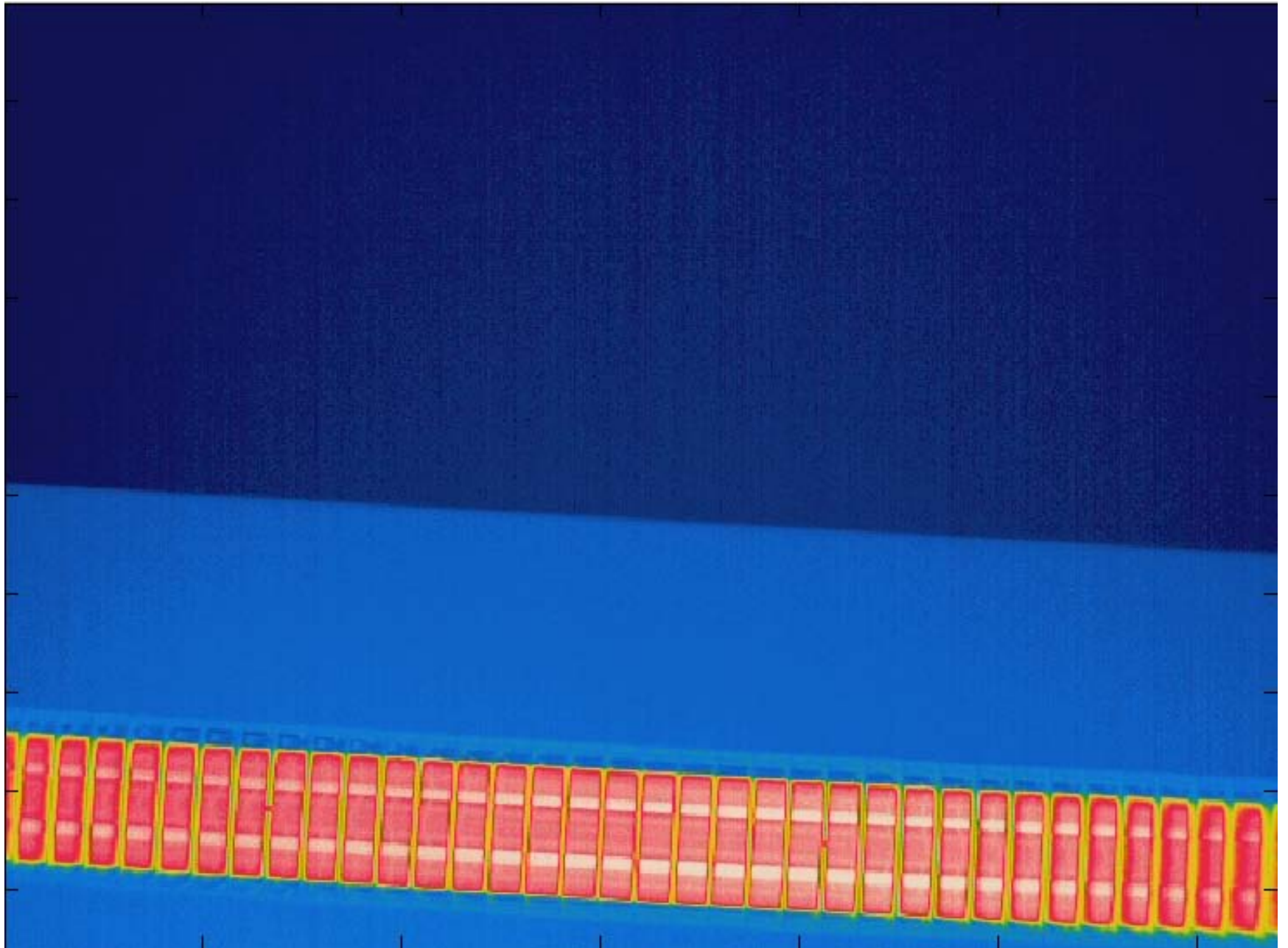


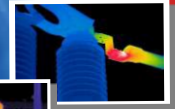
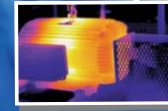
Traditionally: Bad pixel detection during production. Detected pixels stored in a special map with id of replacing pixels.

Ideally: Real time detection
Object dependent replacement.

Single replaced pixels are difficult to see, clusters may be a problem.







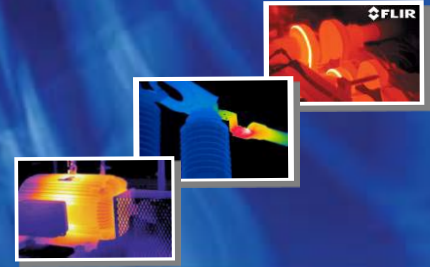
Cooled detectors Usually very low noise

Uncooled

Heavy noise reduction
necessary.

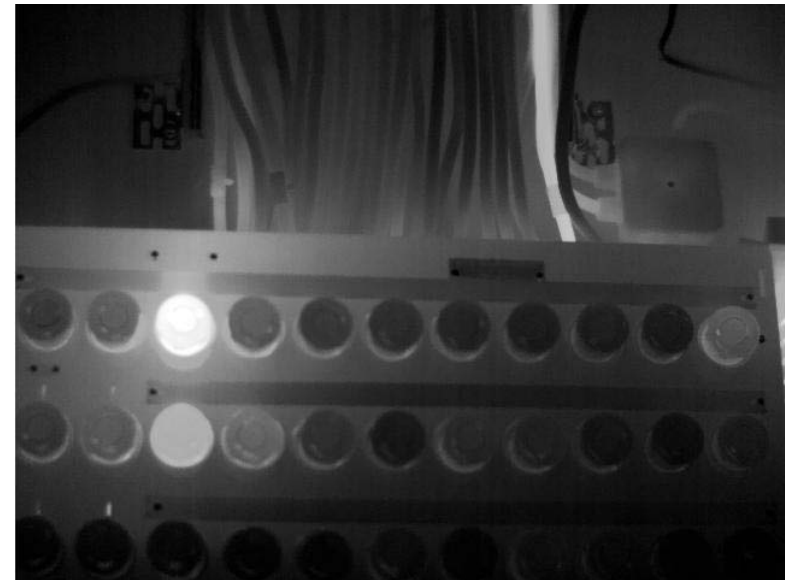
Temporal, spatial and 1/f-noise.

Often problems with correlated
noise (row and column).

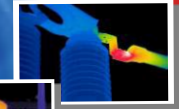
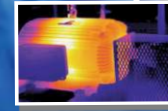


IR is monochromatic, the colour is artificial.

A non-linear colour palett is useful to enhance contrast.



Typical image defects

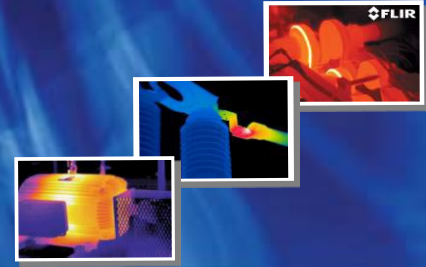


Correlated noise

Image non-uniformity

Shadows

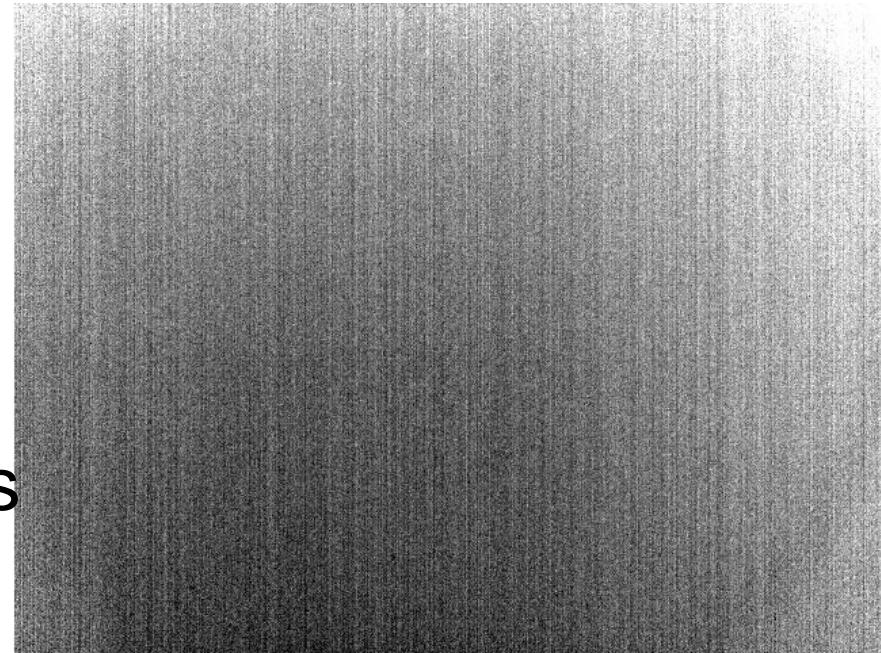
Spots

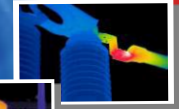
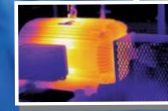


Disturbing row and/or column noise from all uncooled detectors. Often slowly temporal.

Reasons: Imperfections in detector read-out circuits (ROIC)

Solution: Live with it
Digital filter
Blind bolometers

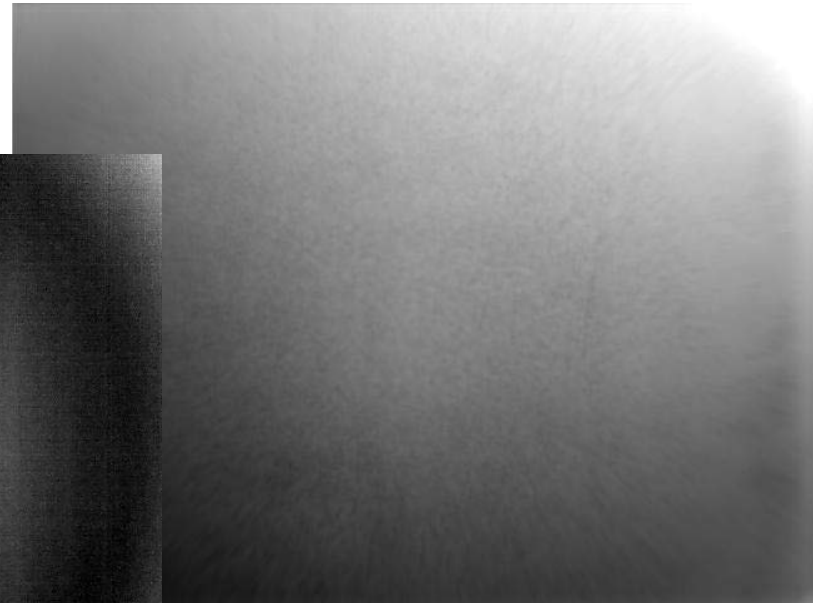
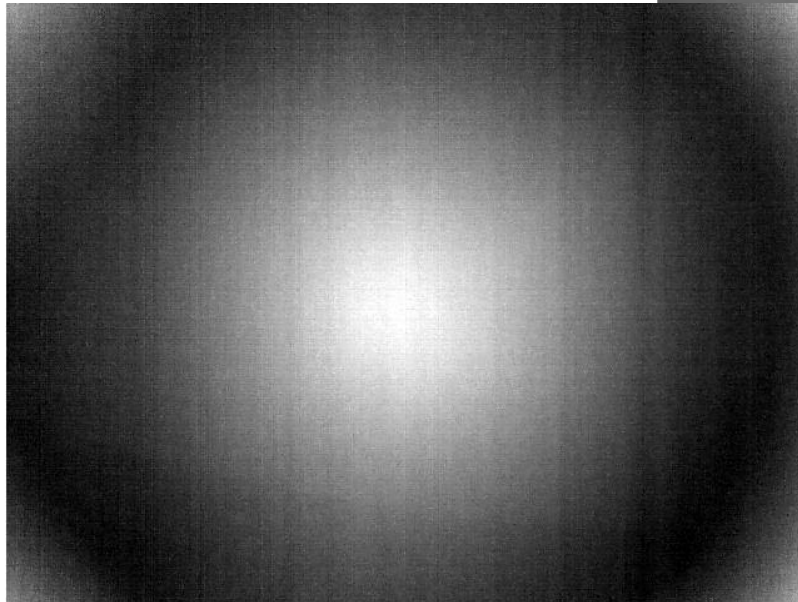


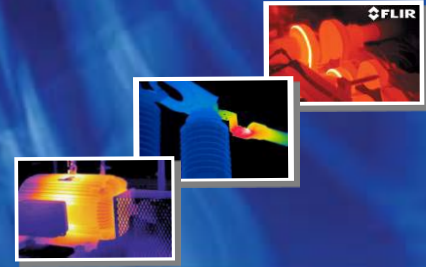


Reasons: Mechanics

Bad optical design

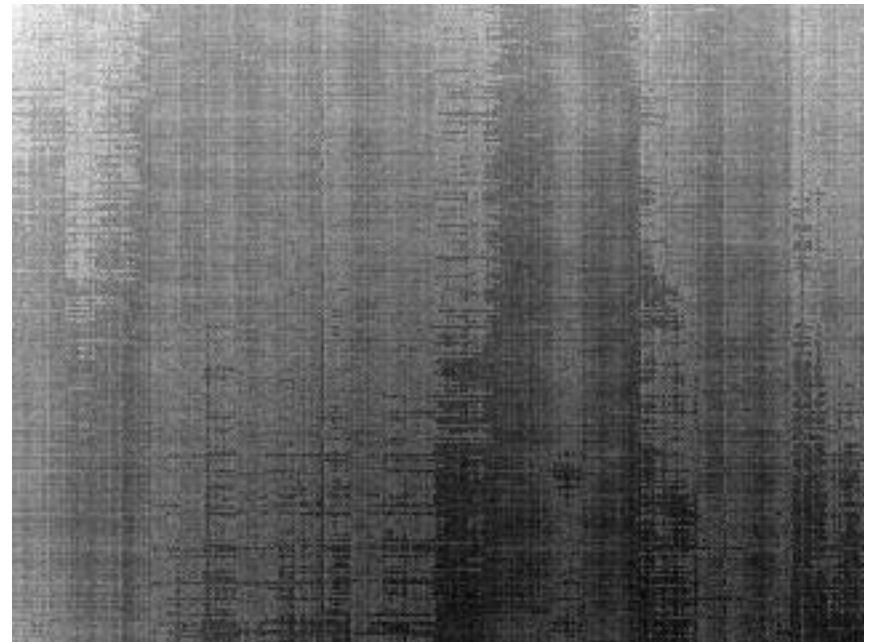
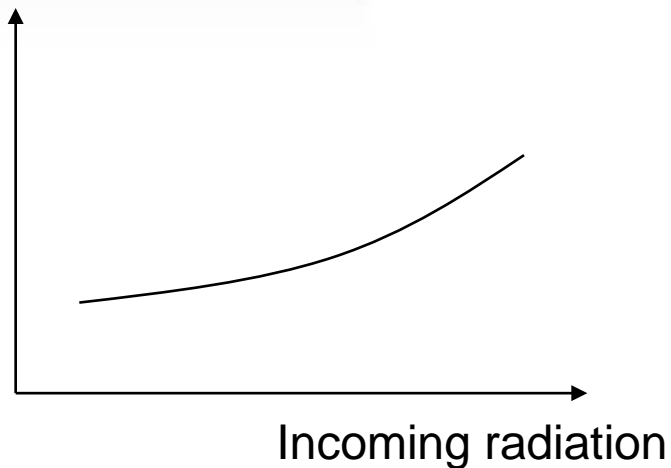
Bad mapping





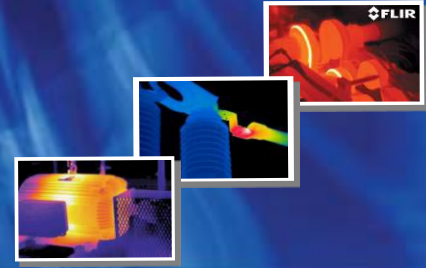
Reason: Nonlinear detector elements

Detector signal

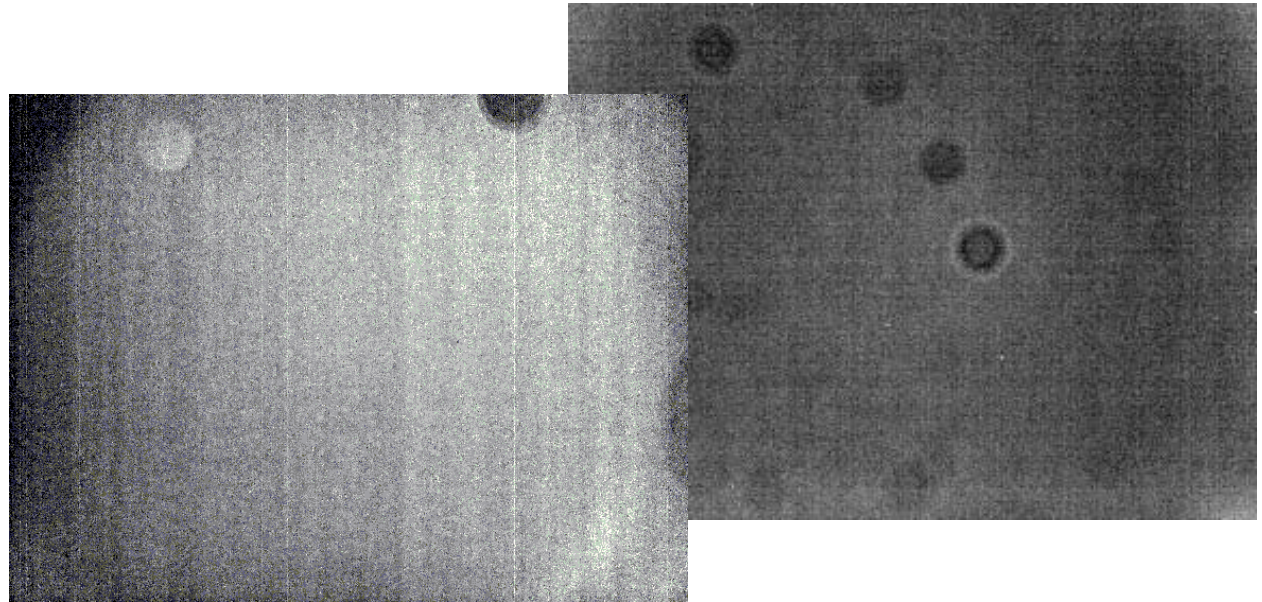


Solution: Usually nothing

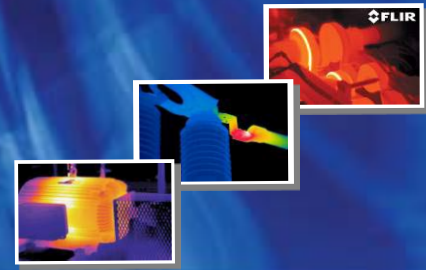
Possible with advanced image processing



Reason: Dust on detector window
Imperfections in the anti reflection coating on the detector window



Solution: Keep the optics clean



Compared to visual images:

Low resolution

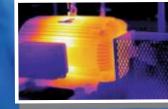
Low contrast

Noisy

No texture

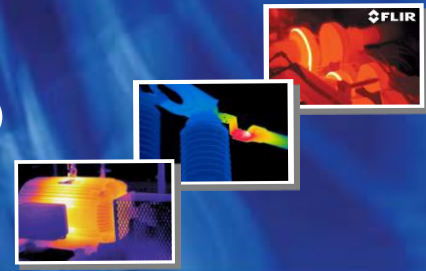
No colour

Typical performance measures, uncooled



- Detector resolution 640x480
- Detector element size 25 μm
- Framerate 30 or 60 Hz
- Temporal noise 30-40 mK
- Measurement accuracy ± 2 degree

Measures and features to compete with



Framerate

Resolution

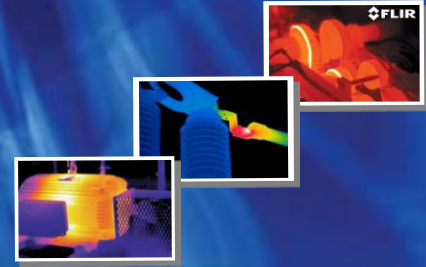
Easy focus

Zoom lens

Features: Multifocus (Avio NEC)

Superresolution (Jenoptics)

Image fusion (Fluke, FLIR, ...)



Specifications

Measuring range -40 to 500°C

Range 1: -20 to 60°C

Range 2: -40 to 120°C

Range 3: 0 to 500°C

Range 4: 200 to 2000°C (optional)

Resolution Range 1: 0.06°C or better at 30°C (30Hz)

Range 2: 0.08°C or better at 30°C (30Hz)

Range 3: 0.12°C or better at 30°C (30Hz)

Accuracy $\pm 2^\circ\text{C}$ or $\pm 2\%$ of reading, whichever is greater

Detector Uncooled focal plane array (microbolometer)

Spectral range 8 to 14 μm

I.F.O.V. 0.6mrad

Focusing range 30cm to infinity

Field of view 21.7°(H) x 16.4°(V)

Frame time 30 frames/sec

Display View finder & 5.6-inch movable color LCD

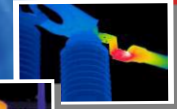
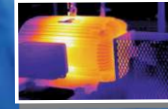
Thermal image pixels 640 (H) x 480 (V) pixels

Emissivity correction Provided (0.10 to 1.00)

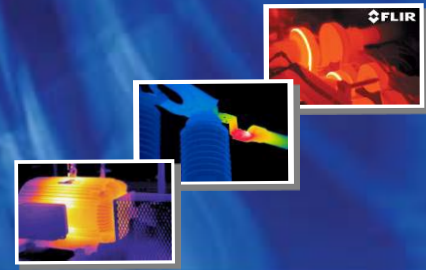
Ambient compensation Provided

Background comp. Provided





Auto functions Full automatic (level, sense, focus)
Isothermal band display Provided (up to 4 bands)
Image processing functions Thermal/visual image fusion display
Multi-point temperature display (up to 10 points)
BOX setting, up to 5 boxes (max, min, average)
Temperature difference between 2 points (Δt)
Visual camera 1.3M pixels, color
Laser pointer
Class 2 (1mW or lower, red)
Video signal output NTSC/PAL, composite video signal, S-video
Interfaces IEEE1394
USB2.0
Compact flash memory card slot
Operating temperature - 15 to 50°C
Shock and vibration Shock: 294m/sec² (30G) (IEC60068-2-27)
Vibration: 29.4m/sec² (3G) (IEC60068-2-6)
Environmental protection IP54 (IEC60529)
Dimension & weight Approx. 110 (W) x 110 (H) x 210 (D) mm
(excluding projections)
1.7kg (including battery)
Standard accessories AC adaptor, battery pack (2 pcs), battery charger,
compact flash memory card (1GB), compact flash
memory card adaptor, carrying case, grip belt,
neck strap, lens cap, viewer software, operation
manual, USB cable, target illuminator



- Decreasing detector prices due to rising volumes
- Increasing volumes due to falling detector prices
- Smaller, lighter cameras
- More built-in-functions
 - Communication
 - Usability
 - Image processing